

# CR-manifolds and Jordan algebras

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## 1. CR-manifolds

Assume that  $E$  is a complex vector space of finite dimension and  $M \subset E$  is a (locally-closed) connected real-analytic submanifold. Then for every  $a \in M$  the tangent space  $T_a M$  is an  $\mathbb{R}$ -linear subspace of  $E$  and  $H_a M := T_a M \cap iT_a M$  is the maximal complex linear subspace of  $E$  contained in  $T_a M$ . The submanifold  $M$  is called a CR-submanifold of  $E$  if the complex dimension of  $H_a M$  does not depend on  $a \in M$ . This dimension is called the CR-dimension of  $M$  and  $H_a M$  is called the holomorphic tangent space at  $a$ , compare [2] as general reference for CR-manifolds. Also, the real dimension of  $T_a M/H_a M$  is called the CR-codimension of  $M$ . For a further real-analytic CR-submanifold  $M'$  of a complex vector space  $E'$  a smooth mapping  $\varphi : M \rightarrow M'$  is called CR if the differential  $d\varphi_a : T_a M \rightarrow T_{\varphi(a)} M'$  maps the corresponding holomorphic tangent spaces in a complex linear way to each other. In terms of differential equations this just means that  $\varphi$  as  $E$ -valued mapping satisfies the Cauchy-Riemann partial differential equations at every point of  $M$  in the direction of the holomorphic tangent space. In particular, in case  $M$  is a complex analytic submanifold of  $E$ , then always  $H_a M = T_a M$  and ‘CR’ just means ‘holomorphic’.

The notion of a CR-function and hence of a CR-mapping can also be reformulated in terms of distributions and then also applies to not necessarily smooth mappings. In particular, due to the approximation theorem of Baouendi-Treves [1]), a continuous map  $\varphi : M \rightarrow M'$  is CR if and only if it is locally the uniform limit of a sequence of smooth CR-mappings. It is a specialty of the Cauchy-Riemann differential equations that compositions of CR-mappings are also CR and, in particular, that the space  $\mathcal{C}_{\text{CR}}(M)$  of all continuous CR-functions  $f : M \rightarrow \mathbb{C}$  is a complex algebra with identity.

Typical questions in this context are for instance: When are two CR-manifolds  $M, M'$  CR-isomorphic, and if so, what is the space of all CR-isomorphisms  $M \rightarrow M'$ . Furthermore, what are the subsets  $A \subset E$  with  $M \subset A$  such that every continuous CR-function on  $M$  has a unique continuous extension to  $A$  that is ‘holomorphic’ in a suitable sense. Also, what is the spectrum (maximal ideal space) of the algebra  $\mathcal{C}_{\text{CR}}(M)$ ?

The following is a well-known example: Let  $E = \mathbb{C}^n$  and  $(z|w) = \sum z_j \bar{w}_j$  the standard hermitian form on  $E$ . Then the unit sphere  $S := \{z \in E : (z|z) = 1\}$  is a CR-submanifold on which the unitary group  $U(n)$  acts transitively by CR-transformations. For every  $a \in S$  the holomorphic tangent space at  $a$  is  $H_a S = \{z \in E : (z|a) = 0\}$  and  $T_a = \mathbb{R}ia \oplus H_a S$ .

## 2. Formally real Jordan algebras and associated CR-manifolds

A real vector space  $V$  together with a symmetric bilinear product  $(x, y) \mapsto x \circ y$  is called a (real) Jordan algebra, if

$$x^2 \circ (x \circ y) = x \circ (x^2 \circ y)$$

holds for all  $x, y \in V$ , where  $x^2 := x \circ x$ . If we denote by  $L_x$  the multiplication operator  $y \mapsto x \circ y$ , then the above equation just means that  $L_x$  and  $L_{x^2}$  commute for every  $x \in V$ . Because of  $2x \circ y = (x+y)^2 - x^2 - y^2$  the Jordan product is uniquely determined by the squaring map  $x \mapsto x^2$  on  $V$ .

The real Jordan algebra  $V \neq 0$  of finite dimension is called formally real [3] or euclidian [5] if  $x^2 + y^2 = 0$  always implies  $x = y = 0$ , or equivalently, if the trace form  $\langle x, y \rangle := \text{tr}(L_x L_y)$  on  $V$  is positive definite. Assume in the following that  $V$  is formally real. Then  $V$  always has an identity  $e$  and there exists an integer  $r \geq 1$  (called the rank of  $V$ ) such that every  $a \in V$  is an  $\mathbb{R}$ -linear combination

$$a = \lambda_1 e_1 + \lambda_2 e_2 + \dots + \lambda_r e_r,$$

where the  $e_1, \dots, e_r$  form an orthogonal family of non-zero idempotents in  $V$  (i.e.  $e_j \circ e_k = \delta_{jk} e_k$ ) with  $e = e_1 + \dots + e_r$ . The coefficients  $\lambda_j$  are uniquely determined up to order and are called the eigenvalues of  $a$ .

For all integers  $p \geq q \geq 0$  with  $0 < p + q \leq r$  we denote by  $C_{p,q}$  the cone of all  $a \in V$  having precisely  $p$  positive and  $q$  negative eigenvalues. Then  $C_{p,q}$  is open in  $V$  if and only if  $p + q = r$ . Of a particular interest is the positive cone  $\Omega := C_{r,0}$ , which is open, convex and coincides with the interior of the closed cone  $\{x^2 : x \in V\}$ . The linear group

$$G = \text{GL}(\Omega) := \{g \in \text{GL}(V) : g(\Omega) = \Omega\}$$

is a reductive Lie group and its connected identity component  $G^0$  acts transitively on every connected component of  $C_{p,q}$ . In particular, every cone  $C_{p,q}$  is a locally linearly homogeneous real-analytic submanifold of  $V$ . Furthermore, the isotropy subgroup

$$\{g \in G : g(e) = e\} = \{g \in \text{GL}(V) : g(x \circ y) = g(x) \circ g(y) \text{ for all } x, y \in V\} =: \text{Aut}(V)$$

at the identity  $e$  is a maximal compact subgroup of  $G$ .

Now denote by  $E := V \oplus iV$  the complexification of  $V$ . The complex bilinear extension of the Jordan product from  $V$  makes  $E$  to a complex Jordan algebra also with identity  $e$ . Denote by

$$D := \Omega \times iV \subset E$$

the tube domain over  $\Omega$  (up to a factor  $i$  a generalized upper halfplane). Then the group  $G \ltimes V$  acts transitively by affine transformations on  $D$  and  $z \mapsto (z - e) \circ (z + e)^{-1}$  defines a biholomorphic mapping from  $D$  to a bounded circular convex domain in  $E$ . Therefore  $D$  is a symmetric tube domain (a bounded symmetric domain of tube type), compare [7], [11] for details. On the other hand, every symmetric tube domain arises from a uniquely determined formally real Jordan algebra in the above way.

$V$  is the direct sum of all its minimal ideals, we may therefore assume without loss of generality in the following that the formally real Jordan algebra  $V$  is simple. Then  $C_{p,q}$  is connected and hence an orbit of the group  $G = \text{GL}(\Omega)$ . Now let

$$M_{p,q} := C_{p,q} \times iV \subset E$$

be the tube manifold over  $C_{p,q}$ . Then the group  $G \ltimes V$  acts transitively on  $M_{p,q}$  by affine transformations and  $M_{p,q}$  is a homogeneous CR-submanifold of  $E$ . Some of the results obtained in [10] can be stated as follows: Suppose that  $V'$  is another simple formally real Jordan algebra of rank  $r'$  and  $p' \geq q' \geq 0$  are integers with  $0 < p' + q' \leq r'$ . Then the tube manifolds  $M_{p,q}$  and  $M'_{p',q'}$  are CR-isomorphic if and only if the Jordan algebras  $V, V'$  are isomorphic and  $p = p'$  as well as  $q = q'$  holds. In case  $p + q < r$  the tube manifolds  $M_{p,q}$  and  $M'_{p',q'}$  are already locally CR-equivalent if and only if they are globally

CR-equivalent. Also in case  $p + q < r$  every continuous CR-function on  $M_{p,q}$  has a unique continuous extension to the convex hull

$$\hat{M}_{p,q} = \begin{cases} E & q > 0 \\ \bigcup_{m \geq p} M_{m,0} & q = 0 \end{cases}$$

of  $M_{p,q}$  that is holomorphic on the interior (compare also Proposition 5.2 in [6] for the last statement).

**2.1 Example.** Let  $H$  be a real Hilbert space of finite dimension  $n \geq 2$ , that is, a real vector space together with a positive definite symmetric bilinear form  $(x, y) \mapsto \langle x|y \rangle$  and corresponding norm  $\|x\| = \sqrt{\langle x|x \rangle}$ . Then  $V := \mathbb{R} \oplus H$  is a simple formally real Jordan algebra of rank 2 with respect to  $(s, x) \circ (t, y) := (st + \langle x|y \rangle, sy + tx)$ . The positive cone is  $\Omega = \{(s, x) \in V : s > \|x\|\}$ , the future cone in  $n+1$ -dimensional space time. Its smooth boundary part is the future light cone  $C_{1,0} = \{(s, x) \in V : s = \|x\| > 0\}$ .

**2.2 Example.** Let  $\mathbb{K}$  be one of the fields  $\mathbb{R}$  or  $\mathbb{C}$  and  $\mathcal{H}_r(\mathbb{K}) := \{x \in \mathbb{K}^{r \times r} : x = x^*\}$  the  $\mathbb{R}$ -linear space of all hermitian  $r \times r$ -matrices over  $\mathbb{K}$ . Then  $V := \mathcal{H}_r(\mathbb{K})$  is a simple formally real Jordan algebra of rank  $r$  with respect to  $x \circ y := (xy + yx)/2$ . The notion of eigenvalue and inverse coincides with the usual one for matrices. In particular,  $\Omega$  is the open cone of positive definite matrices.

Example 2.2 can be extended by taking  $\mathcal{H}_r(\mathbb{H})$  for the skew-field  $\mathbb{H}$  of quaternions and also by  $\mathcal{H}_3(\mathbb{O})$  for the division algebra  $\mathbb{O}$  of octonions. Together with these extensions the above examples give a complete list of all simple formally real Jordan algebras.

### 3. Hermitian Jordan triple systems

For the next bunch of CR-manifolds let us recall the classical singular value decomposition of rectangular matrices: Fix integers  $n \geq r \geq 1$  and let  $E := \mathbb{C}^{r \times n}$  be the space of all complex  $r \times n$ -matrices. Then to every  $a \in E$  there exist unitary matrices  $u \in U(r)$  and  $v \in U(n)$  such that  $d := uav \in E$  is a real diagonal matrix with diagonal entries  $d_{11} \geq d_{22} \geq \dots \geq d_{rr} \geq 0$ , called the singular values of  $a$ . In particular, for every  $a \neq 0$  the subset  $S \subset E$  of all matrices having the same singular values as  $a$  is a generalization of the euclidian spheres in  $\mathbb{C}^n$  (which occur for  $r = 1$ ).

A singular value decomposition exists in every positive hermitian Jordan triple system. This is a complex vector space  $E$  of finite dimension together with a map (called Jordan triple product)

$$E \times E \times E \rightarrow E, \quad (x, y, z) \mapsto \{xyz\},$$

that satisfies the following properties, compare [11]:

- (i)  $\{xyz\}$  is symmetric complex bilinear in the outer variables  $x, z$  and conjugate linear in the inner variable  $y$ ,
- (ii)  $\{ab\{xyz\}\} = \{\{abx\}yz\} - \{x\{bay\}z\} + \{xy\{abz\}\}$  for all  $a, b, x, y, z \in E$ ,
- (iii)  $\{xxx\} = \lambda x$  implies  $x = 0$  or  $\lambda \in e^{\mathbb{R}}$  for all  $x \in E$  and  $\lambda \in \mathbb{C}$ .

Examples are for instance every  $E = \mathbb{C}^{r \times n}$  with  $\{xyz\} = (xy^*z + zy^*x)/2$ , but also the subspaces  $\{z \in \mathbb{C}^{n \times n} : z' = z\}$  of all symmetric, as well as  $\{z \in \mathbb{C}^{n \times n} : z' = -z\}$  of all skew-symmetric  $n \times n$ -matrices with the triple product restricted from  $\mathbb{C}^{n \times n}$ . Also, for every formally real Jordan algebra  $V$  the complexification  $E = V \oplus iV$  becomes a positive hermitian Jordan triple system with respect to the triple product  $\{xyz\} = (x \circ \bar{y}) \circ z + (z \circ \bar{y}) \circ x - x^2 \circ \bar{y}$ , where  $y \mapsto \bar{y}$  is the conjugation of  $E$  with respect to the real form  $V$  of  $E$ .

Now fix an arbitrary positive hermitian Jordan triple system  $E \neq 0$ . The element  $e \in E$  is called a tripotent if  $\{eee\} = e$  holds. Two tripotents  $e, c \in E$  are called orthogonal if  $\{eec\} = 0$ , or equivalently, if  $\{cce\} = 0$  holds. There exists an integer  $r \geq 1$ , called the rank of  $E$ , such that every  $a \in E$  has a representation

$$a = \sigma_1 e_1 + \sigma_2 e_2 + \dots + \sigma_r e_r +$$

with pairwise orthogonal non-zero tripotents  $e_1, e_2, \dots, e_r$  and uniquely determined real coefficients

$$\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_r \geq 0.$$

For every  $k$  with  $1 \leq k \leq r$  the number  $\sigma_k(a) := \sigma_k$  is called the  $k^{\text{th}}$  singular value of  $a$ . It is known that for every  $k$  the sum  $\alpha_k := \sigma_1 + \sigma_2 + \dots + \sigma_r : E \rightarrow \mathbb{R}$  defines a norm on  $E$ . In particular, the open unit ball  $D := \{z \in E : \sigma_1(z) < 1\}$  with respect to the norm  $\sigma_1 = \alpha_1$  is homogeneous under biholomorphic automorphisms and hence a bounded symmetric domain, compare [7] and [11] for details. On the other hand, every bounded symmetric domain occurs as the open  $\sigma_1$ -unit ball of a suitable positive hermitian Jordan triple system  $E$ .

The triple automorphism group

$$\text{Aut}(E) := \{g \in \text{GL}(E) : g\{xyz\} = \{(gx)(gy)(gz)\} \text{ for all } x, y, z\}$$

is compact and coincides with the group of all  $\sigma_1$ -isometries of  $E$ . Clearly,  $\text{Aut}(E)$  leaves invariant the mapping  $\sigma := (\sigma_1, \dots, \sigma_r) : E \rightarrow \mathbb{R}^r$ . Denote by  $K$  the connected identity component of  $\text{Aut}(E)$ . In case of  $E = \mathbb{C}^{r \times n}$ , for instance,  $K$  is the group of all transformations  $z \mapsto uzv$  with  $u \in \text{U}(r)$  and  $v \in \text{U}(n)$ .

Since  $E$  is the direct sum of its minimal ideals (the linear subspace  $I \subset E$  is called an ideal, if  $\{IEE\} + \{EIE\} \subset I$ ) we assume in the following that  $E$  is simple, or equivalently, that  $K$  acts irreducibly on  $E$ . For every  $s$  in

$$\Delta := \{s \in \mathbb{R}^r : 1 = s_1 \geq s_2 \geq \dots \geq s_r \geq 0\}$$

the set

$$M_s := \{z \in E : \sigma(z) = s\}$$

is a  $K$ -orbit and hence a homogeneous CR-submanifold of  $E$ . On the other hand, every non-zero  $K$ -orbit obviously is of the form  $t \cdot M_s$  for uniquely determined  $t > 0$  and  $s \in \Delta$  and hence is CR-equivalent to  $M_s$ . The following statements can be found in [9] and [8].

For every  $a \in M_s$  The linear convex hull of  $M_s$  is given by

$$\text{ch}(M_s) = \{z \in E : \alpha_k(z) \leq \alpha_k(a) \text{ for all } k\}.$$

If the multiplicative analogon to the norms  $\alpha_k$  is defined as the product  $\mu_k := \sigma_1 \sigma_2 \cdots \sigma_k$  then the polynomial convex hull of  $M_s$  can be written as

$$\text{pch}(M_s) = \{z \in E : \mu_k(z) \leq \mu_k(a) \text{ for all } k\}.$$

For the formulation of further results one has to distinguish the two cases  $a \in E$  invertible and  $a \in E$  non-invertible. By definition,  $a$  is invertible in  $E$  if the conjugate linear operator  $z \mapsto \{aza\}$  is invertible on  $E$  (in case  $E = \mathbb{C}^{r \times n}$  invertibility of  $a$  is just the usual notion for matrices, i.e.  $r = n$  and  $\det(a) \neq 0$ ).

For simplicity let us assume for the rest of the section that  $a \in M_s$  and hence every element of  $M_s$  is non-invertible. Then  $M_s$  is a minimal Levi-nondegenerate CR-manifold and is CR-isomorphic to  $M_t$ ,  $t \in \Delta$ , if and only if  $t = s$ . Also, every continuous CR-function  $f$  on  $M_s$  has a unique continuous extension to the polynomial convex hull  $\text{pch}(M_s)$  which is holomorphic in a certain sense (in particular is holomorphic in the usual sense on the interior of  $\text{pch}(M_s) \subset E$  if not empty). In fact,  $\text{pch}(M_s)$  can be canonically be identified with the spectrum of the Banach algebra  $\mathcal{C}_{\text{CR}}(M_s)$ .

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